

# Kouds HALITIM

## PhD student in control of HPC systems

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## SKILLS

<b>Control Systems</b>	Linear/non-linear, stochastic, adaptive & robust control
<b>Programming</b>	C, C++, Python, MATLAB, R
<b>Databases</b>	MySQL
<b>Tools &amp; DevOps</b>	Git, Docker, Make, Nix, VS Code
<b>Operating Systems</b>	Windows 11, Linux Ubuntu

## WORK EXPERIENCE

<b>Present</b> Nov. 2023	<b>PhD Candidate in Control of HPC systems, INRIA</b> Ctrl-A Team, Inria, LIG, Univ. Grenoble Alpes, Grenoble, France
<b>Sept. 2023</b> March 2023	<b>Research Intern, INRIA</b> Spirals Team, Inria, Lille, France
<b>Jan. 2023</b> Dec. 2022	<b>Industrial Automation Intern, Sonatrach</b> Sonatrach, Skikda, Algeria
<b>March 2022</b> April 2022	<b>Embedded Systems Intern, Brandt</b> Brandt, Sétif, Algeria
<b>April 2021</b> March 2021	<b>Instrumentation Intern, IRIS</b> IRIS, Sétif, Algeria

## EDUCATION

<b>November 2026</b> (Expected)	<b>PhD in Computer Science, INRIA</b> Ctrl-A Team, Inria, LIG, Univ. Grenoble Alpes, Grenoble, France. "Efficient task hybridization in heterogeneous computing : a practical combination of control and scheduling theories." Supervised by : Eric Rutten, Raphael Bleuse, and Bogdan Robu. <ul style="list-style-type: none"><li>&gt; Developed models for large-scale distributed systems (HPC) to account for system dynamics, resource constraints, and thermal uncertainties.</li><li>&gt; Synthesized and implemented controllers to regulate trade-offs between file system congestion, resource harvesting and power consumption.</li><li>&gt; Designed a Stochastic Model Predictive Control framework to optimize task injection under high uncertainty and variable workload conditions.</li><li>&gt; Formulated I/O interference as a control problem and implemented regulation mechanisms for multi-client environments to ensure performance isolation.</li><li>&gt; Built large-scale experimental testbeds and automated data collection to validate theoretical models against state-of-the-art heuristics.</li><li>&gt; Conducted robustness analyses and comparative evaluations to assess the stability, performance and scalability of implemented controllers.</li><li>&gt; Designed a hierarchical regulation framework for processor power capping that ensures energy budget compliance across variable system dimensions and hardware configurations.</li></ul>
<b>September 2023</b>	<b>Master's and Engineering Degree, ENP</b> National Polytechnic School, Algiers, Algeria. Specialization in Automatic Control. <ul style="list-style-type: none"><li>&gt; Advanced Control Systems</li><li>&gt; Optimization and Optimal Control</li><li>&gt; Industrial Process Control</li></ul>

- > Signal Processing
- > Industrial Computing
- > Programming (C, C++, Python)
- > Instrumentation
- > Process Identification
- > Multivariable Control (State-space/Frequency domain)
- > Power Electronics
- > Robotics
- > Programmable Logic Controllers (PLC)
- > Control Systems Technology
- > Discrete Event Systems

September 2018 | **High School Diploma in Mathematics and Physics, with Honors**  
Fatima Zahra High School, Sétif, Algeria

## TEACHING

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|-------------------------------------|---|
| <p>June 2026<br/>September 2024</p> | <p><b>Discrete-Time Control Systems, Lab Sessions - 18 hours</b></p> <ul style="list-style-type: none"> <li>&gt; Developed comprehensive lab curricula and source code for a digital motion control lab, integrating micro-controllers with real-time data processing.</li> <li>&gt; Mentored diverse student groups (15-20) by applying theoretical control concepts to real-world experimental scenarios.</li> <li>&gt; Collaborated proactively with the teaching team to improve educational materials.</li> </ul>  |
| <p>June 2026<br/>September 2024</p> | <p><b>Continuous-Time Control Systems, Lab Sessions - 59 hours</b></p> <ul style="list-style-type: none"> <li>&gt; Contributed to the drafting and updating of laboratory workbooks.</li> <li>&gt; Created digital supporting resources on MATLAB/Simulink to facilitate the adoption of calculation and simulation tools.</li> <li>&gt; Commissioned, tested, and configured specific testbeds (PID Controllers and Rotating Machines) and experimental rigs (DC motors, sensors).</li> <li>&gt; Led the full control design process : modeling, experimental identification, and PID synthesis to meet performance criteria.</li> </ul>   |
| <p>April 2026</p>                   | <p><b>Software Engineering Project, Project Tutor - 5.5 hours</b></p> <ul style="list-style-type: none"> <li>&gt; Supervised student teams in the full-cycle development of strategy game software.</li> <li>&gt; Mentored groups on Agile methodologies : task planning, workload distribution, and conflict resolution.</li> <li>&gt; Provided technical oversight on the implementation of Minimax algorithms and heuristic optimization.</li> <li>&gt; Guided the design and validation of Graphical User Interfaces (GUI) using user-centered testing.</li> <li>&gt; Evaluated technical deliverables, including code quality, architectural robustness, and documentation.</li> <li>&gt; Acted as a member of the final defense jury to assess project outcomes and technical presentations.</li> </ul> |

## SUPERVISION

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| <p>2026</p> | <p><b>Doaa Elnoamany</b> : “<i>Control of uncertain MIMO systems with probabilistic constraints...</i>”<br/>Master of Science (M.Sc.) MiSCIT, Université Grenoble Alpes, Grenoble, France.<br/>Co-encadrement : Bogdan Robu and Sophie Cerf</p>                                       |
| <p>2025</p> | <p><b>Mohamed Abdeljalil Maziz</b> : “<i>LPV control for dynamic power capping in High-Performance Computing (HPC) under mixed workloads</i>”<br/>Master of Science (M.Sc.) MiSCIT, Université Grenoble Alpes, Grenoble, France.<br/>Co-encadrement : Bogdan Robu and Sophie Cerf</p> |
| <p>2025</p> | <p><b>Mahmoud Abdo</b> : “<i>Model Predictive Control (MPC) approach for resource scavenging in High-Performance Computing (HPC)</i>”<br/>Master of Science (M.Sc.) MiSCIT, Université Grenoble Alpes, Grenoble, France.<br/>Co-encadrement : Bogdan Robu and Sophie Cerf</p>         |

## PUBLICATIONS

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### International Conferences

- [C1] **K. Halitim**, T. Collignon, S. Cerf, B. Robu, E. Rutten, R. Bleuse, “Event-Triggered Adaptive PI Control for Mitigating Congestion in Shared Storage Systems”, in ECC 2026 - European Control Conference, Reykjavik, Iceland, 2026. (Accepted).
- [C2] **K. Halitim**, S. Cerf, B. Robu, and É. Rutten, “Robust Cascade Control for Variable Dimension Systems - Application to processors’ power capping”, in ECC 2025 - European Control Conference, Thessaloniki, Greece, 2025. Available : <https://hal.science/hal-05117585v1>
- [C3] **K. Halitim**, B. Robu, S. Cerf, R. Bleuse, E. Rutten, “Stochastic Model Predictive Control with Direct Feedforward Compensation”, in ICSTCC 2025 - 29th International Conference on System Theory, Control and Computing, Cluj-Napoca, Romania, 2025. Available : <https://hal.science/hal-05210549v1>
- [C4] T. Collignon, **K. Halitim**, R. Bleuse, S. Cerf, B. Robu, É. Rutten, L. Seinturier, and A. van Kempen, “Mitigating Shared Storage Congestion Using Control Theory”, in UCC 2025 - IEEE/ACM International Conference on Utility and Cloud Computing, Nantes, France, Dec. 2025. Available : <https://cnrs.hal.science/LIG/hal-05368563v1>

### National Conferences

- [N1] T. Collignon, **K. Halitim**, R. Bleuse, S. Cerf, B. Robu, É. Rutten, L. Seinturier, and A. van Kempen, “Coarse-grain Congestion Regulation Using Control Theory”, in COMPAS 2025 - Conférence en Parallélisme, Architecture et Système, Bordeaux, France, 2025. Available : <https://hal.science/hal-05075480v1>

### Theses

- [T1] **Kouids Halitim**. “Enhancing Efficiency through Control Theory in Compute-Intensive Applications,” Master’s Thesis, 2023. Available : <https://inria.hal.science/hal-04357812>

### Posters

- [P1] T. Collignon, **K. Halitim**, R. Bleuse, S. Cerf, B. Robu, É. Rutten, L. Seinturier, and A. van Kempen, “Temperature control of computing sites through the injection of useful and non-invasive tasks”, Greendays 2026, March 2026, Sophia, France. Available : <https://inria.hal.science/hal-05551250v1>
- [P2] **Kouids Halitim**. “Task hybridization in heterogeneous computing : a combination of control and scheduling theories”, “PAD Days” GIPSA, December 2025, GRENOBLE (38000), France.
- [P3] **Kouids Halitim**. “Task hybridization in heterogeneous computing : a combination of control and scheduling theories”, “PhD Madness” LIG, May 2025, GRENOBLE (38000), France. Available : <https://inria.hal.science/hal-05108245v1>

## SCIENTIFIC RESPONSIBILITIES

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- 2025 | Reviewer for the European Control Conference (ECC 2025) and the International Conference on Utility and Cloud Computing (UCC 2025)
- 2025 | Session Chair for the “Control Applications” session at the European Control Conference (ECC 2025)
- 2026 | Session Chair for the “Heterogeneous and reconfigurable architectures for the future of computing: Project Talks” session at the 18<sup>th</sup> JLESC workshop

## LANGUAGES

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- French** : Fluent
- English** : Fluent
- Arabic** : Native
- German** : Beginner